Factor Graphs and message passing

Carl Edward Rasmussen

October 28th, 2016

- Factor graphs are a class of graphical model
- A factor graph represents the product structure of a function, and contains factor nodes and variable nodes
- We can compute marginals and conditionals efficiently by passing messages on the factor graph, this is called the sum-product algorithm (a.k.a. belief propagation or factor-graph propagation)
- We can apply this to the True Skill graph
- But certain messages need to be approximated
- One approximation method based on moment matching is called Expectation Propagation (EP)

Factor Graphs

Factor graphs are a type of *probabilistic graphical model* (others are directed graphs, a.k.a. Bayesian networks, and undirected graphs, a.k.a. Markov networks).

Factor graphs allow to represent the product structure of a function. Example: consider the factorising probability distribution:

 $p(v, w, x, y, z) = f_1(v, w) f_2(w, x) f_3(x, y) f_4(x, z)$

A factor graph is a bipartite graph with two types of nodes:

- Factor node: Variable node: ○
- Edges represent the dependency of factors on variables.



Factor Graphs



- What are the marginal distributions of the individual variables?
- What is p(w)?
- How do we compute conditional distributions, e.g. p(w|y)?

For now, we will focus on *tree-structured* factor graphs.

Factor trees: separation (1)



$$p(w) = \sum_{v} \sum_{x} \sum_{y} \sum_{z} f_1(v, w) f_2(w, x) f_3(x, y) f_4(x, z)$$

- If w, v, x, y and z take K values each, we have $\approx 3K^4$ products and $\approx K^4$ sums, for each value of w, i.e. total $O(K^5)$.
- Multiplication is distributive: ca + cb = c(a + b). The right hand side is more efficient!

Factor trees: separation (2)



$$p(w) = \sum_{v} \sum_{x} \sum_{y} \sum_{z} f_1(v, w) f_2(w, x) f_3(x, y) f_4(x, z)$$
$$= \left[\sum_{v} f_1(v, w) \right] \cdot \left[\sum_{x} \sum_{y} \sum_{z} f_2(w, x) f_3(x, y) f_4(x, z) \right]$$

- In a tree, each node separates the graph into disjoint parts.
- Grouping terms, we go from sums of products to products of sums.
- The complexity is now $\mathcal{O}(K^4)$.

Factor trees: separation (3)



• Sums of products becomes products of sums of all messages from neighbouring factors to variable.

Messages: from factors to variables (1)



$$\mathbf{m}_{\mathbf{f}_2 \to \mathbf{w}}(\mathbf{w}) = \sum_{\mathbf{x}} \sum_{\mathbf{y}} \sum_{\mathbf{z}} f_2(\mathbf{w}, \mathbf{x}) f_3(\mathbf{x}, \mathbf{y}) f_4(\mathbf{x}, \mathbf{z})$$

Messages: from factors to variables (2)



$$\begin{split} \mathfrak{m}_{\mathfrak{f}_{2} \to \mathfrak{w}}(\mathfrak{w}) &= \sum_{x} \sum_{y} \sum_{z} f_{2}(w, x) f_{3}(x, y) f_{4}(x, z) \\ &= \sum_{x} f_{2}(w, x) \cdot \underbrace{\left[\sum_{y} \sum_{z} f_{3}(x, y) f_{4}(x, z)\right]}_{\mathfrak{m}_{x \to f_{2}}(x)} \end{split}$$

• Factors only need to sum out all their local variables.

Messages: from variables to factors (1)



$$\mathfrak{m}_{\mathbf{x}\to f_2}(\mathbf{x}) = \sum_{y} \sum_{z} f_3(x, y) f_4(x, z)$$

Messages: from variables to factors (2)



$$\begin{split} \mathfrak{m}_{\mathbf{x} \to \mathfrak{f}_{2}}(\mathbf{x}) &= \sum_{y} \sum_{z} f_{3}(x, y) f_{4}(x, z) \\ &= \underbrace{\left[\sum_{y} f_{3}(x, y)\right]}_{\mathfrak{m}_{f_{2} \to x}(\mathbf{x})} \cdot \underbrace{\left[\sum_{z} f_{4}(x, z)\right]}_{\mathfrak{m}_{f_{4} \to x}(\mathbf{x})} \end{split}$$

• Variables pass on the product of all incoming messages.

Factor graph marginalisation: summary



• The complexity is reduced from $O(K^5)$ (naïve implementation) to $O(K^2)$.

The sum-product algorithm

In summary, message passing involved three update equations:

• Marginals are the product of all incoming messages from neighbour factors

$$p(t) = \prod_{f \in F_t} \mathfrak{m}_{f \to t}(t)$$

• Messages from factors sum out all variables except the receiving one

$$\mathfrak{m}_{f \rightarrow t_1}(t_1) = \sum_{t_2} \sum_{t_3} \dots \sum_{t_n} f(t_1, t_2, \dots, t_n) \prod_{i \neq 1} \mathfrak{m}_{t_i \rightarrow f}(t_i)$$

• Messages from variables are the product of all incoming messages except the message from the receiving factor

$$\mathfrak{m}_{t \to f}(t) = \prod_{f_j \in F_t \setminus \{f\}} \mathfrak{m}_{f_j \to t}(t) = \frac{\mathfrak{p}(t)}{\mathfrak{m}_{f \to t}(t)}$$

Messages are results of partial computations. Computations are localised.